Multiple Linear Regression: Least squares and non-linearity

Author: Nicholas G Reich, Jeff Goldsmith

This material is part of the statsTeachR project

Made available under the Creative Commons Attribution-ShareAlike 3.0 Unported License: http://creativecommons.org/licenses/by-sa/3.0/deed.en_US

Today's topics

- least squares for MLR: geometry, "hat matrix"
- collinearity and non-identifiability
- introduction to modeling non-linear relationships

Example predicting respiratory disease severity ("lung" dataset) Holding off on inference/diagnostics for another week...

Multiple linear regression model

• Observe data $(y_i, x_{i1}, \dots, x_{ip})$ for subjects $1, \dots, n$. Want to estimate $\beta_0, \beta_1, \dots, \beta_p$ in the model

$$y_i = \beta_0 + \beta_1 x_{i1} + \ldots + \beta_1 x_{ip} + \epsilon_i; \ \epsilon_i \stackrel{iid}{\sim} (0, \sigma^2)$$

Déjà vu: MLR assumptions

Assumptions

- Residuals have mean zero, constant variance, are independent
- Often assuming linearity
- Our primary interest will be $E(y|\mathbf{x})$
- Estimation using least squares

Déjà vu: Least squares

As in simple linear regression, we want to find the $oldsymbol{eta}$ that minimizes the residual sum of squares.

$$RSS(\beta) = \sum_{i} \epsilon_{i}^{2} = \epsilon^{T} \epsilon$$

After taking the derivative, setting equal to zero, we obtain:

$$\hat{oldsymbol{eta}} = (\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y}$$

Déjà vu: Sampling distribution of $\hat{oldsymbol{eta}}$

If our usual assumptions are satisfied and $\epsilon \stackrel{\it iid}{\sim} N\left[0,\sigma^2\right]$ then

$$\hat{\boldsymbol{\beta}} \sim \mathsf{N}\left[\boldsymbol{\beta}, \sigma^2(\mathbf{X}^T\mathbf{X})^{-1}\right].$$

- This will be used later for inference.
- Even without Normal errors, asymptotic Normality of LSEs is possible under reasonable assumptions.

Déjà vu: Definitions

- Fitted values: $\hat{\mathbf{y}} = \mathbf{X}\hat{\boldsymbol{\beta}} = \mathbf{X}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y} = \mathbf{H}\mathbf{y}$
- lacksquare Residuals / estimated errors: $\hat{m{\epsilon}} = {f y} \hat{f y}$
- Residual sum of squares: $\sum_{i=1}^{n} \hat{\epsilon_i}^2 = \hat{\epsilon}^T \hat{\epsilon}$
- Residual variance: $\hat{\sigma^2} = \frac{RSS}{n-p-1}$
- Degrees of freedom: n p 1

Déjà vu: R^2 and sums of squares

- Regression sum of squares $SS_{reg} = \sum (\hat{y}_i \bar{y})^2$
- Residual sum of squares $SS_{res} = \sum (y_i \hat{y}_i)^2$
- Total sum of squares $SS_{tot} = \sum (y_i \bar{y})^2$
- Coefficient of determination

$$R^{2} = 1 - \frac{\sum (y_{i} - \hat{y}_{i})^{2}}{\sum (y_{i} - \bar{y})^{2}} = \frac{\sum (\hat{y}_{i} - \bar{y})^{2}}{\sum (y_{i} - \bar{y})^{2}}$$

Not so Déjà vu: the "Hat matrix"

Some properties of the hat matrix:

- It is a projection matrix: **HH** = **H**
- It is symmetric: $\mathbf{H}^T = \mathbf{H}$
- The residuals are $\hat{\epsilon} = (\mathbf{I} \mathbf{H})\mathbf{y}$
- The inner product of (I H)y and Hy is zero (predicted values and residuals are uncorrelated).

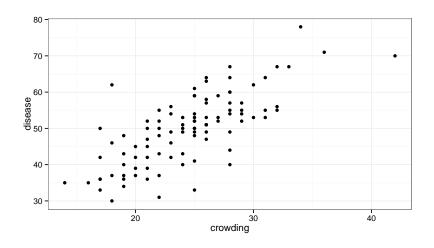
Projection space interpretation

The hat matrix projects \mathbf{y} onto the column space of \mathbf{X} . Alternatively, minimizing the $RSS(\beta)$ is equivalent to minimizing the Euclidean distance between \mathbf{y} and the column space of \mathbf{X} .

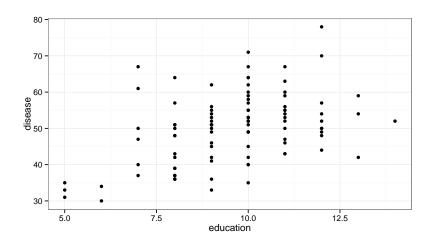
99 observations on patients who have sought treatment for the relief of respiratory disease symptoms. The dependent variable, The variables are:

- disease measure of disease severity (larger values indicates more serious condition).
- education highest grade completed
- crowding measure of crowding of living quarters (larger values indicate more crowding)
- airqual measure of air quality at place of residence (larger number indicates poorer quality)
- nutrition nutritional status (larger number indicates better nutrition)
- smoking smoking status (1 if smoker, 0 if non-smoker)

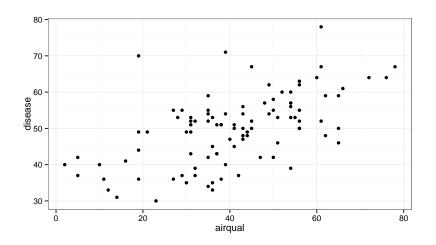
qplot(crowding, disease, data=dat)



qplot(education, disease, data=dat)



qplot(airqual, disease, data=dat)



```
mlr1 <- lm(disease ~ crowding + education + airqual,
          data=dat, x=TRUE, y=TRUE)
coef(mlr1)
## (Intercept) crowding education airqual
## -7.7505215 1.3127837 1.4376563 0.2880687
X = mlr1$x
v = mlr1$v
(beta_hat = solve(t(X)%*%X) %*% t(X) %*% y )
                    [,1]
##
## (Intercept) -7.7505215
## crowding 1.3127837
## education 1.4376563
## airqual 0.2880687
```

Least squares estimates: identifiability

$$\hat{oldsymbol{eta}} = \left(\mathbf{X}^{\mathcal{T}} \mathbf{X}
ight)^{-1} \mathbf{X}^{\mathcal{T}} \mathbf{y}$$

A condition on $(\mathbf{X}^T\mathbf{X})$: must be invertible

- If $(\mathbf{X}^T\mathbf{X})$ is singular, there are infinitely many least squares solutions, making $\hat{\boldsymbol{\beta}}$ non-identifiable (can't choose between different solutions)
- In practice, true non-identifiability (there really are infinite solutions) is rare.
- More common, and perhaps more dangerous, is collinearity.

Causes of non-identifiability

- Can happen if X is not of full rank, i.e. the columns of X are linearly dependent (for example, including weight in Kg and lb as predictors)
- Can happen if there are fewer data points than terms in X:
 n
- Generally, the $p \times p$ matrix $(\mathbf{X}^T \mathbf{X})$ is invertible if and only if it has rank p.

Infinite solutions

Suppose I fit a model $y_i = \beta_0 + \beta_1 x_{i1} + \epsilon_i$.

- I have estimates $\hat{\beta}_0 = 1, \hat{\beta}_1 = 2$
- I put in a new variable $x_2 = x_1$
- My new model is $y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \epsilon_i$
- Possible least squares estimates that are equivalent to my first model:
 - $\hat{\beta}_0 = 1, \hat{\beta}_1 = 2, \hat{\beta}_2 = 0$
 - $\hat{\beta}_0 = 1, \hat{\beta}_1 = 0, \hat{\beta}_2 = 2$
 - $\hat{\beta}_0 = 1, \hat{\beta}_1 = 1002, \hat{\beta}_2 = -1000$
 - **.** . . .

Non-identifiability example: lung data

```
mlr3 <- lm(disease ~ airqual, data=dat)</pre>
coef(mlr3)
## (Intercept) airqual
## 35.4444812 0.3537389
dat$x2 <- dat$airqual/100
mlr4 <- lm(disease ~ airqual + x2, data=dat, x=TRUE)
coef (mlr4)
## (Intercept) airqual
                                 x2
## 35.4444812 0.3537389
                                   NΑ
X = mlr4$x
solve( t(X) %*% X)
## Error in solve.default(t(X) %*% X): system is computationally
singular: reciprocal condition number = 3.57906e-20
```

Non-identifiablity: causes and solutions

- Often due to data coding errors (variable duplication, scale changes)
- Pretty easy to detect and resolve
- Can be addressed using penalties (might come up much later)
- A bigger problem is near-unidentifiability (collinearity)

Diagnosing collinearity

- Arises when variables are highly correlated, but not exact duplicates
- Commonly arises in data (perfect correlation is usually there by mistake)
- Might exist between several variables, i.e. a linear combination of several variables exists in the data
- A variety of tools exist (correlation analyses, multiple R^2 , eigen decompositions)

Effects of collinearity

Suppose I fit a model $y_i = \beta_0 + \beta_1 x_{i1} + \epsilon_i$.

- I have estimates $\hat{\beta}_0 = 1, \hat{\beta}_1 = 2$
- I put in a new variable $x_2 = x_1 + error$, where *error* is pretty small
- My new model is $y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \epsilon_i$
- Possible least squares estimates that are nearly equivalent to my first model:
 - $\hat{\beta}_0 = 1, \hat{\beta}_1 = 2, \hat{\beta}_2 = 0$
 - $\hat{\beta}_0 = 1, \hat{\beta}_1 = 0, \hat{\beta}_2 = 2$
 - $\hat{\beta}_0 = 1, \hat{\beta}_1 = 1002, \hat{\beta}_2 = -1000$
 - **•** ...
- A unique solution exists, but it is hard to find

Effects of collinearity

- Collinearity results in a "flat" RSS
- Makes identifying a unique solution difficult
- Dramatically inflates the variance of LSEs

Collinearity example: lung data

```
dat$crowd2 <- dat$crowding + rnorm(nrow(dat), sd=.1)</pre>
mlr5 <- lm(disease ~ crowding, data=dat)
summary(mlr5)$coef
##
        Estimate Std. Error t value Pr(>|t|)
## (Intercept) 12.991536 3.4750250 3.738544 3.130355e-04
## crowding 1.508806 0.1393709 10.825836 2.231686e-18
mlr6 <- lm(disease ~ crowding + crowd2, data=dat)
summary(mlr6)$coef
              Estimate Std. Error t value Pr(>|t|)
##
## (Intercept) 13.019617 3.490168 3.7303699 0.0003236495
## crowding -1.510590 6.883739 -0.2194432 0.8267707628
## crowd2 3.017039 6.876945 0.4387180 0.6618516741
```

Some take away messages

- Collinearity can (and does) happen, so be careful
- Often contributes to the problem of variable selection, which we'll touch on later

Non-linear relationships: polynomial regression

Many relationships between X and Y are non-linear. A simple (not necessarily the best) way to account for this is using polynomial forms of X.

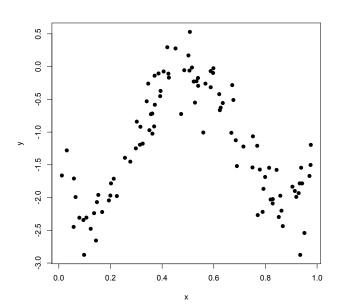
Model of the form

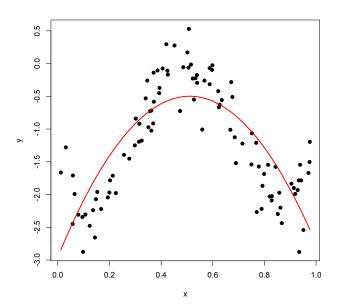
$$y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \ldots + \beta_p x_i^p + \epsilon_i; \ \epsilon_i \stackrel{iid}{\sim} (0, \sigma^2)$$

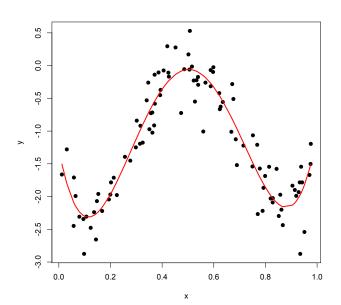
- p is the polynomial order
- More polynomial terms can lead to a better approximation of E(y|x), but also higher variability in the fit
- Conversely, smaller p can lead to inability to capture E(y|x), but is often more stable
- Quadratic and cubic fits are relatively common

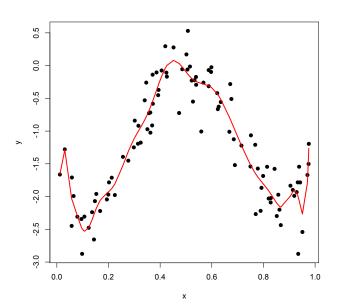
Some tips on non-linear relationships

- You can go as high as p = n, but don't do it! "Overfitting" data is common practice (unfortunately).
- Coefficients become harder to interpret you can't increase x_2 without changing every other x_p
- Better (maybe) to think of the model as an estimated curve, whose interpretation is related to the derivative
- The literal formulation above is numerically unstable. Better to use orthogonal polynomials (R's poly function)

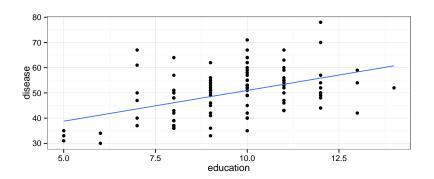


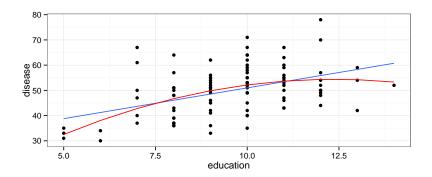






```
(p <- ggplot(dat, aes(x=education, y=disease)) + geom_point() +
    geom_smooth(method="lm", se=FALSE) )</pre>
```

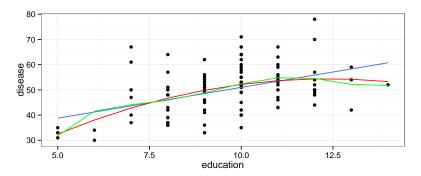




```
mlr4 <- lm(disease ~ poly(education, 5), data=dat)
coef(mlr4)

## (Intercept) poly(education, 5)1 poly(education, 5)2
## 49.919192 43.951707 -18.469208
## poly(education, 5)3 poly(education, 5)4 poly(education, 5)5
## -4.131932 -4.651902 7.896361

(p <- p + geom_line(aes(y=predict(mlr4)), color="green"))
```



Smoothing and splines

Turns out there's a lot of work on estimating smooth E(y|x) = f(x)

- Rather than polynomials, use smooth spline basis functions with nice properties (stable, smooth, flexible, smooth derivatives)
- These are piecewise polynomials
- How many to use governs how smooth or wiggly the final fit is
- Can introduce explicit penalties for smoothness, which gets you into semi-parametric regression ...

Today's big ideas

- least squares geometry, "hat matrix"
- dangers of collinearity and non-identifiability
- polynomial regression to model non-linear relationships

Lab

Analyze the NHANES dataset. Create a model with the outcome variable of cholesterol (chol) that estimates relationships with other variables in the dataset.

library(NHANES)
data(NHANES)
?NHANES